

ABSTRACT OF THE DISCLOSURE

There is provided a control circuit for
arithmetically processing at least one of focus-
directional and tracking-directional position error
signals, and adding the arithmetic operation result as
an input amount to a coil for driving in the opposite
direction. The control circuit produces such a control
signal as to cancel the effect of an oscillation mode
of an objective lens holder. An output determination
circuit temporarily restricts functions of the control
circuit when the determination circuit has determined
that a disturbance component is mixed in the position
error signal. Thereby, even in the case of slight
displacement, the objective lens can be controlled
independently in the focusing and tracking directions
while avoiding interference movement in both directions.

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